



# The Planning of Ground Delay Programs Subject to Uncertain Capacity

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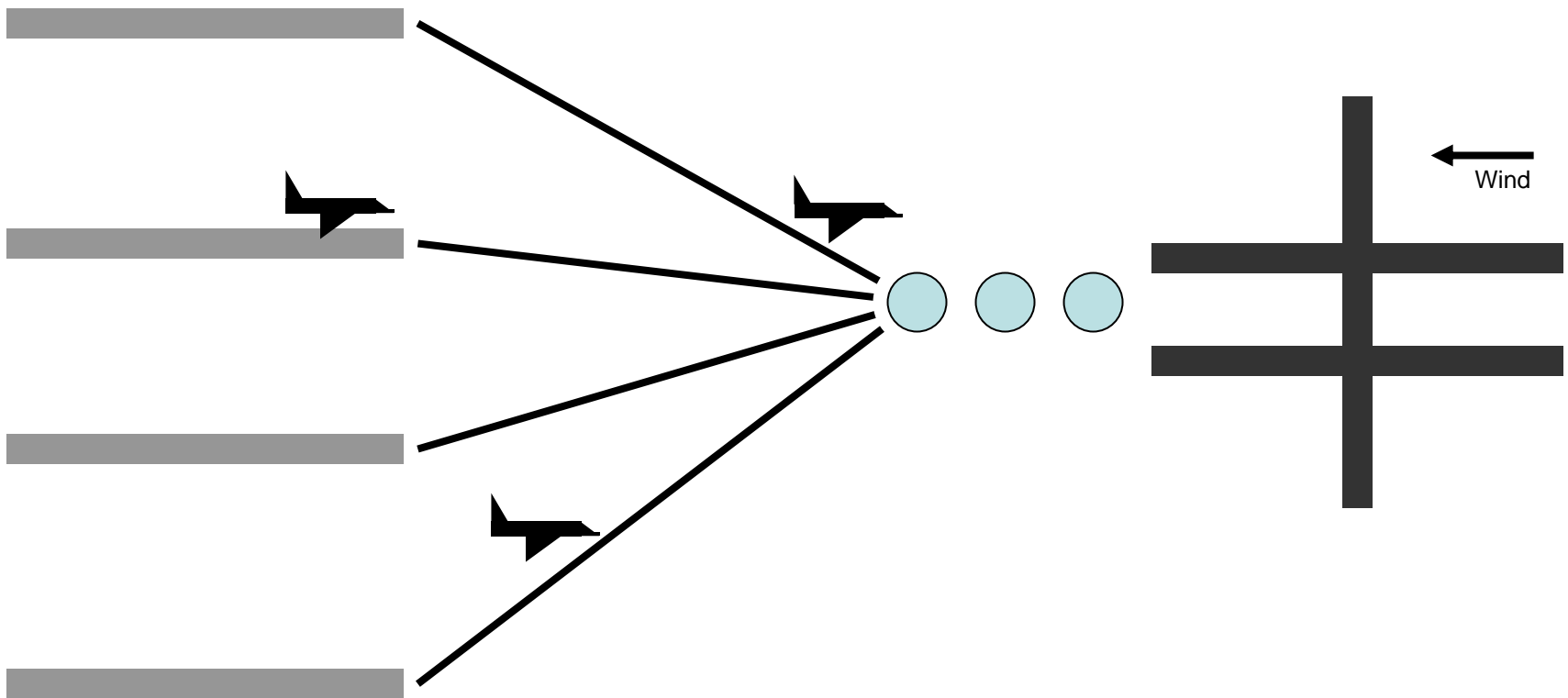
- Introduction
  - Ground Delay Programs
  - Decision Tradeoffs
  - Mathematical Approach:
- Initial application
  - Airborne Queue Size
  - Total Delay Cost
  - Unavoidable Delay
  - Delay Distribution
- Conclusions



# Delays occur when arrival demand exceeds capacity

Demand Rate: 50 ac/hour

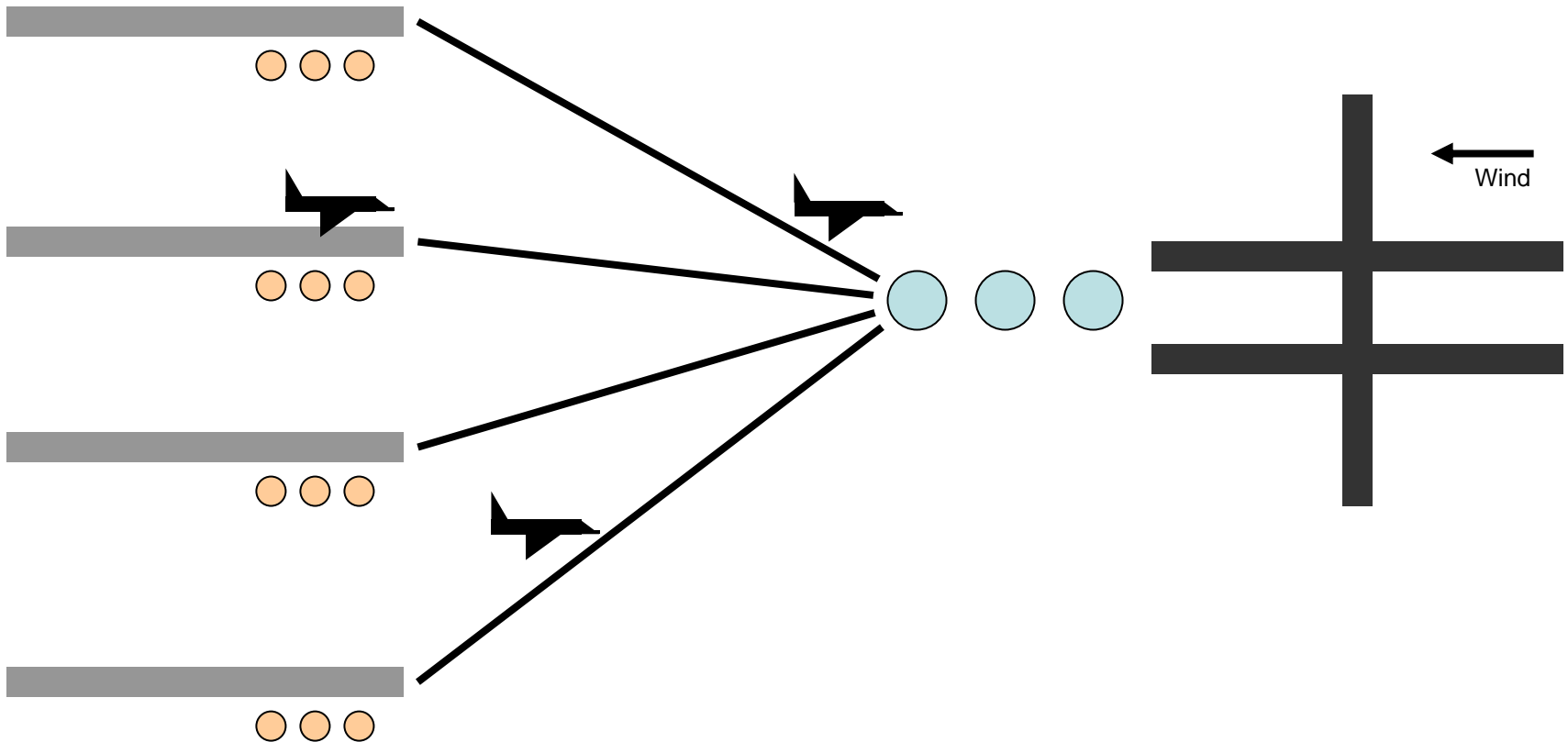
Arrival Rate: 60 ac/hour



# GDPs create ground delays to avoid those in the air

Demand Rate: 50 ac/hour

Arrival Rate: 60 ac/hour

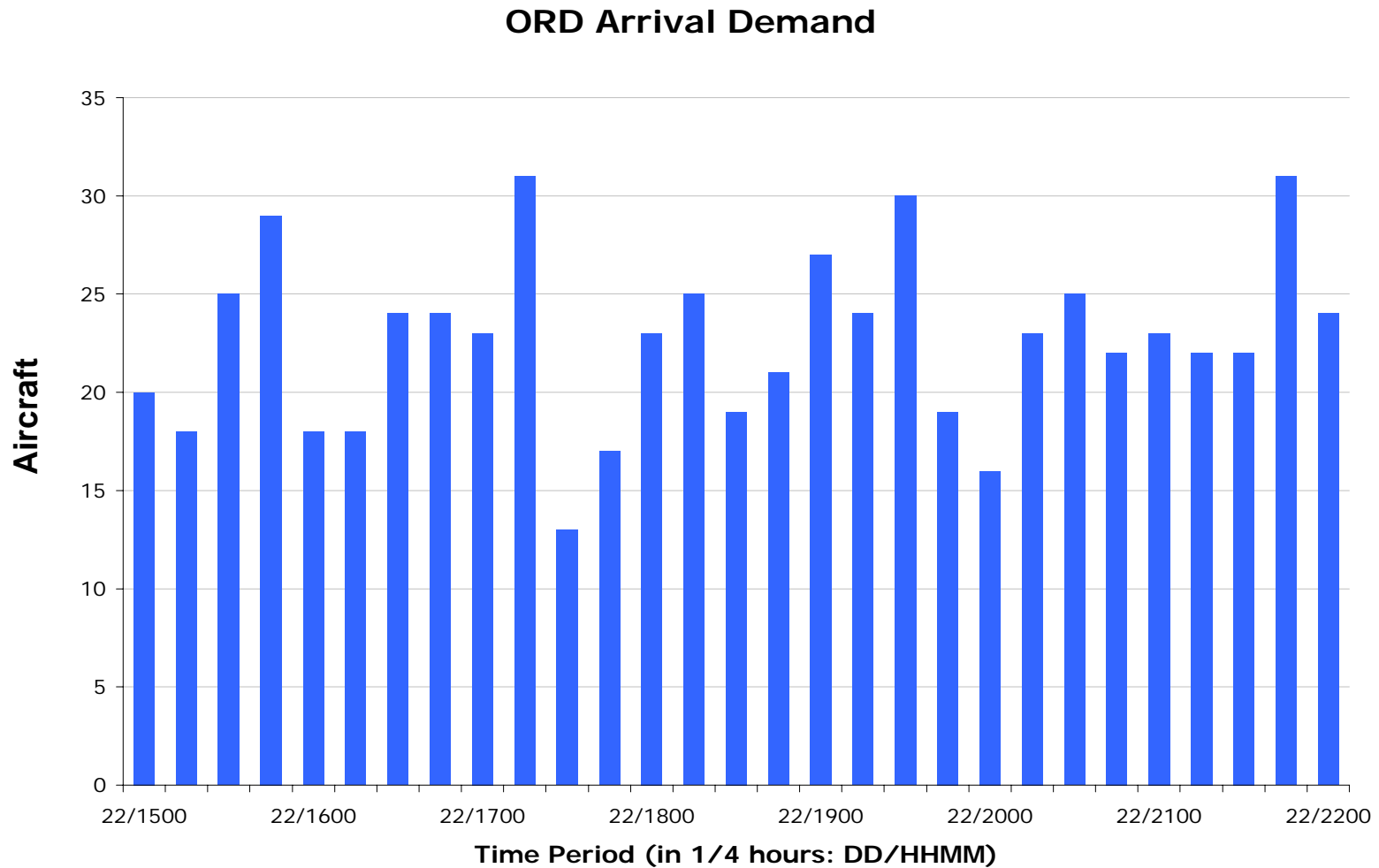


# GDP design balances two key tradeoffs

- How much ground delay should be assigned?
  - Too much causes additional, unnecessary delays
  - Too little and expensive airborne delays may occur
- When should the GDP be created?
  - Waiting means that flights depart and cannot be delayed
  - Additional, improved capacity information becomes available over time

**GDPs are both stochastic and dynamic**

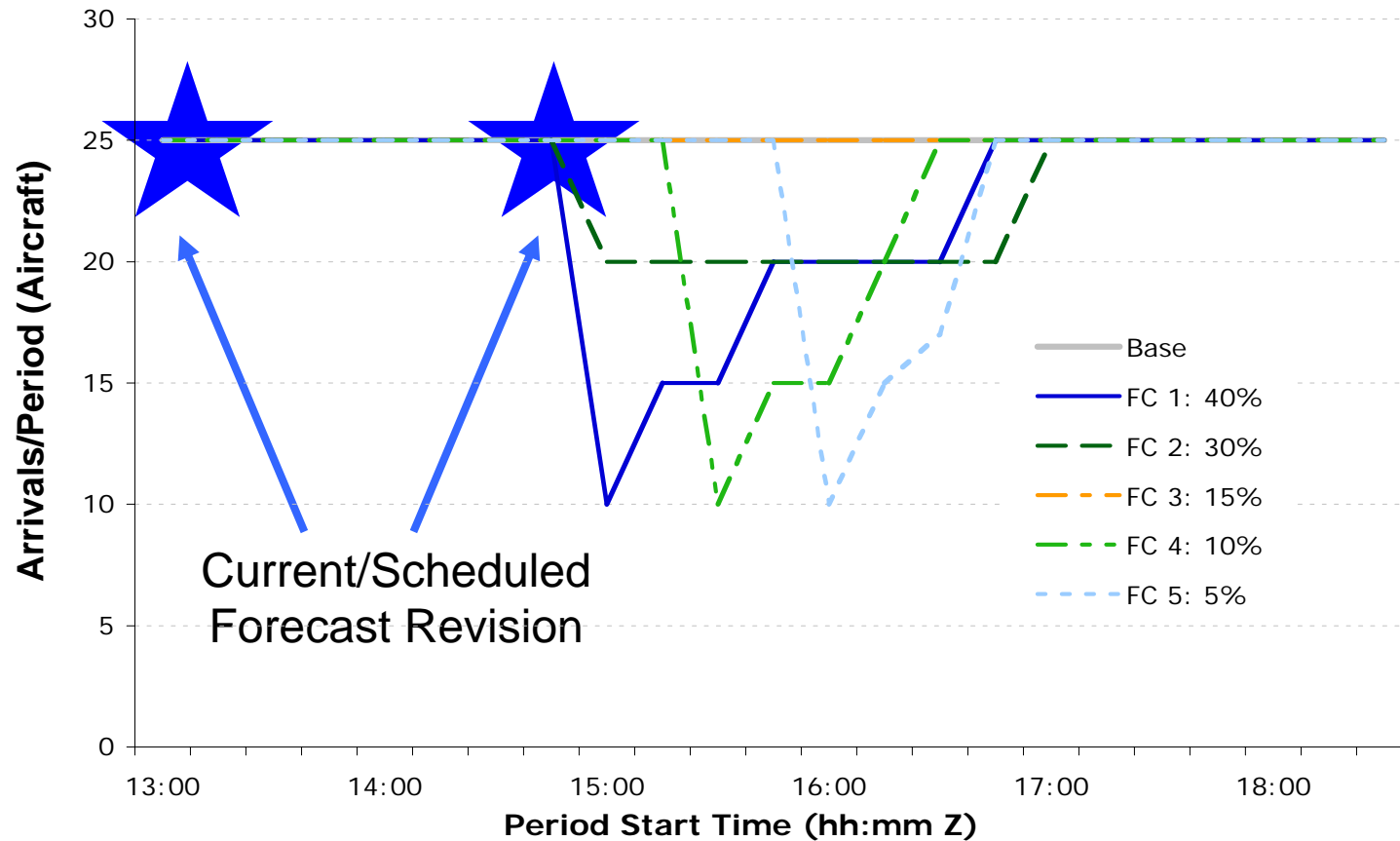
# A numerical example: arrival demand over time



Source: ETMS, June 22nd, 14:45 Z, aggregated by author

# A numerical example: arrival capacity scenario

## Scenario of Airport Capacity Profiles by Time Period



# Full Odoni Richetta (1993) formulation

Minimize: 
$$\sum_{q=1}^Q p_q \left\{ \sum_{k=1}^K \sum_{s=1}^Q \sum_{i=t_s+1}^T \sum_{j=i+1}^{T+1} C_g(k, j-i) \times \chi_{qksij} + c_a \sum_{i=1}^T W_{qi} \right\}$$

Subject to: 
$$\chi_{skzij} = \chi_{s+1ksij} = \dots = \chi_{Qksij} \quad \forall s = 1 \dots Q-1; i = t_s + 1 \dots T; i \leq j \leq T+1; q = 1 \dots Q; k = 1 \dots K$$

$$\sum_{j=i}^{T+1} \chi_{qksij} = N_{ksi} \quad \forall k = 1 \dots K; s = 1 \dots Q; i = t_s + 1 \dots T$$

$$\sum_{i=1}^{T+1} S_{qi} = \sum_{i=1}^T M_{qi}$$

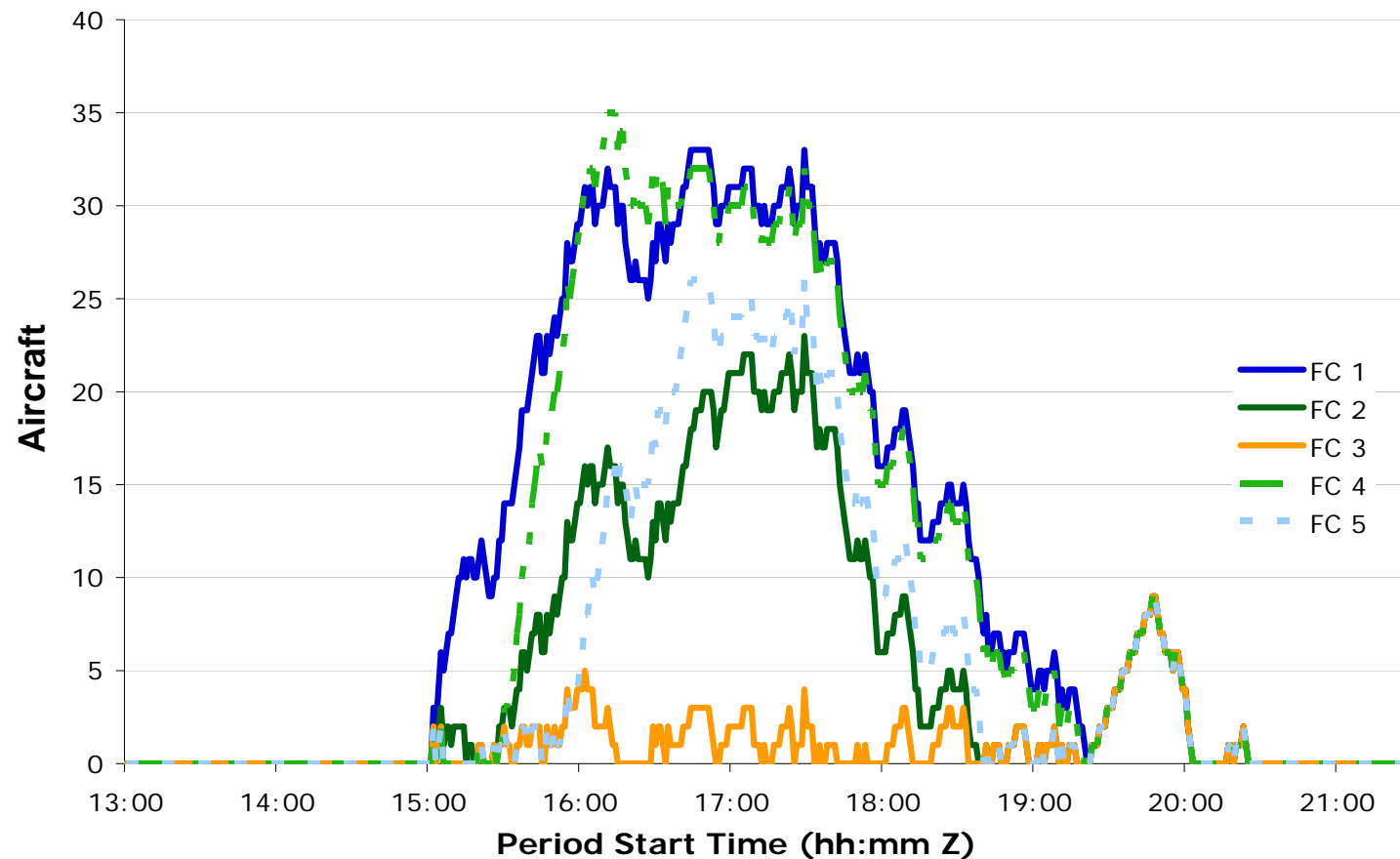
$$W_{qi} - W_{qi-1} - \sum_{k=1}^K \sum_{s:t_s < i} \sum_{j=t_s+1}^i \chi_{qksji} - S_{qi} = -M_{qi} \quad \forall i = 1 \dots T+1$$

$$W_{q0} = W_{qT+1} = 0$$

$$\chi_{qksij}, W_{qi}, S_{qi} \geq 0$$

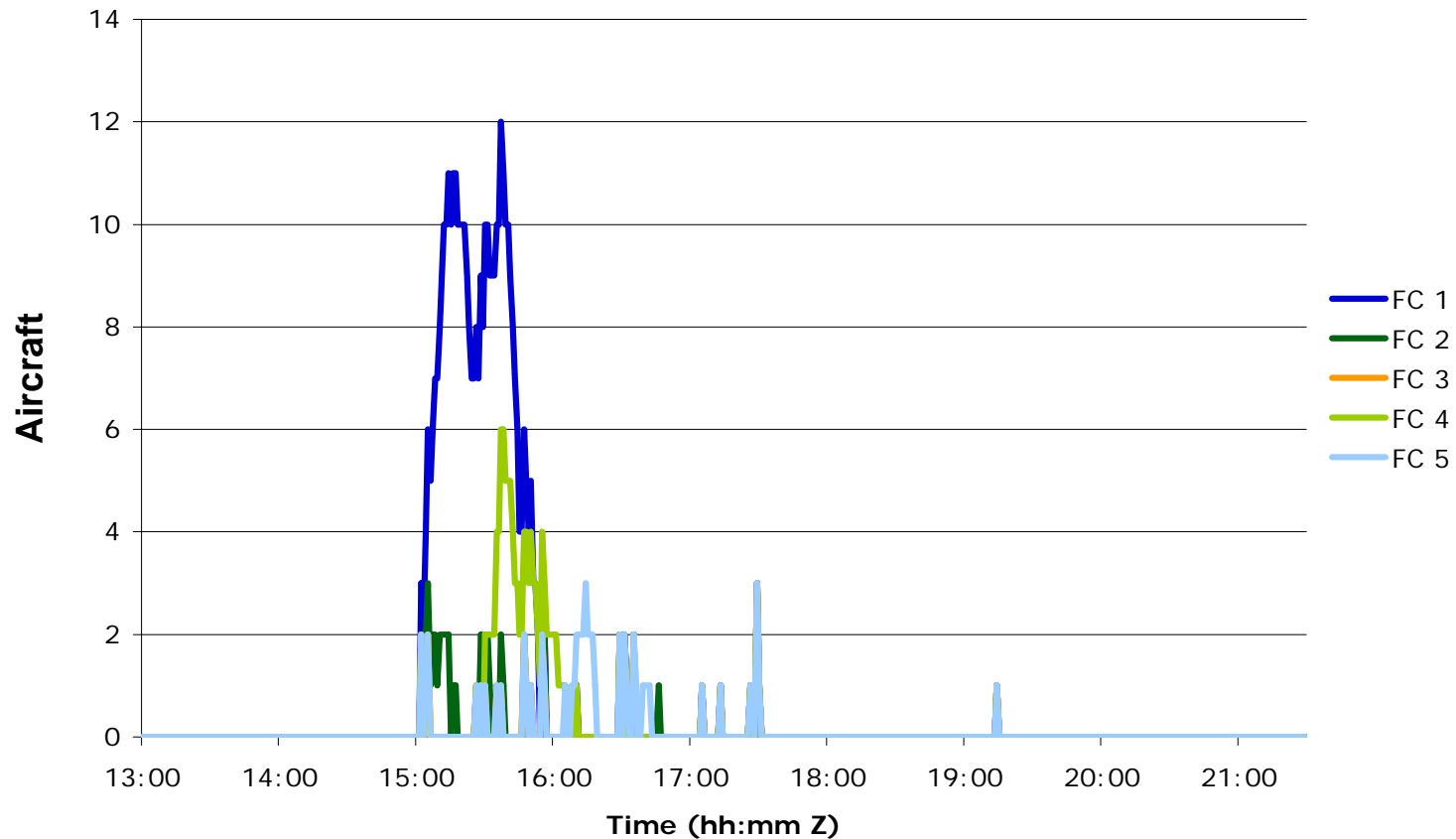
# Queue Size – without a GDP

## Scenario Arrival Queues by Time



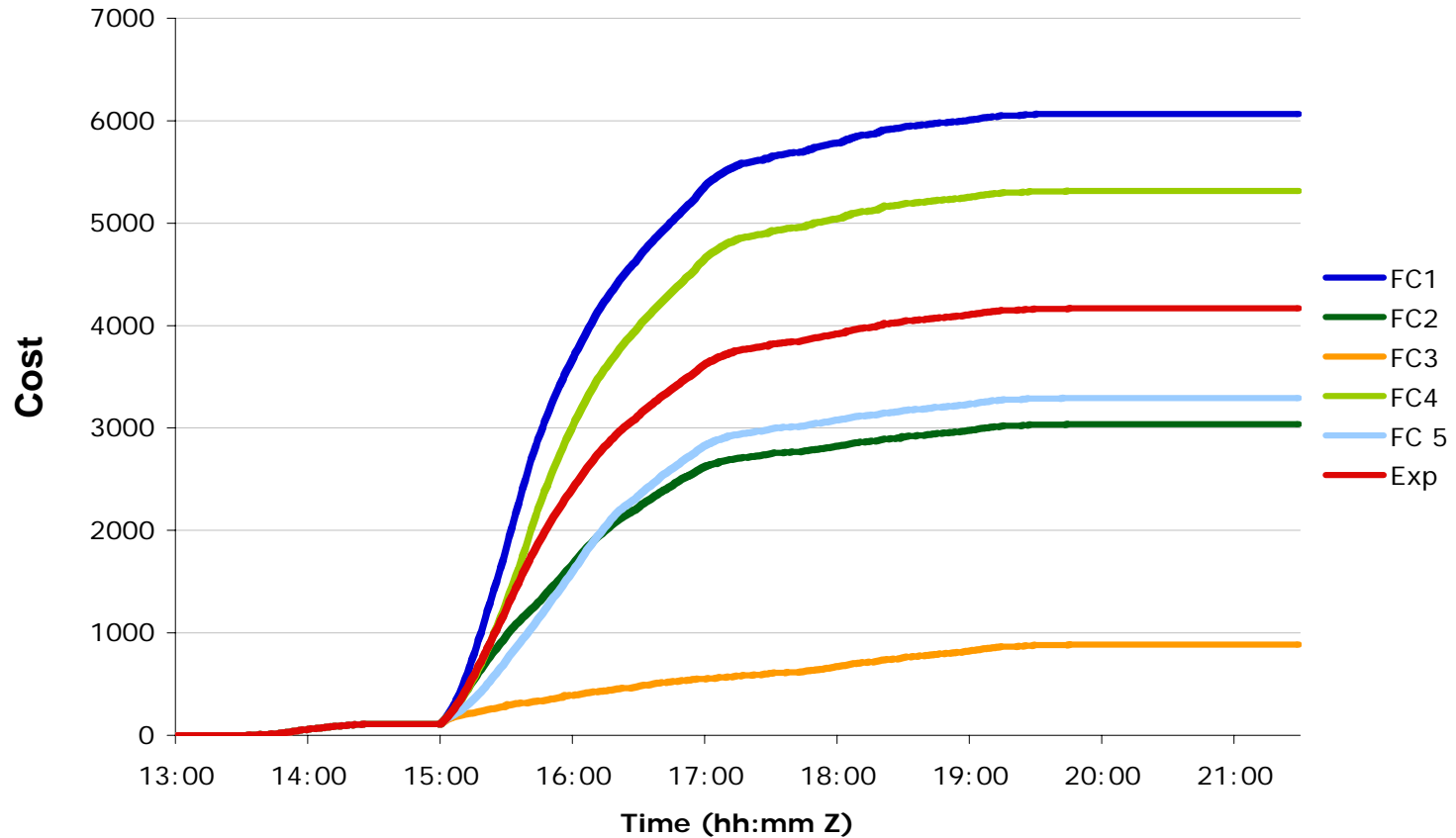
# Queue Size – with the proposed GDP

## Airborne Queue Size by Capacity Profile



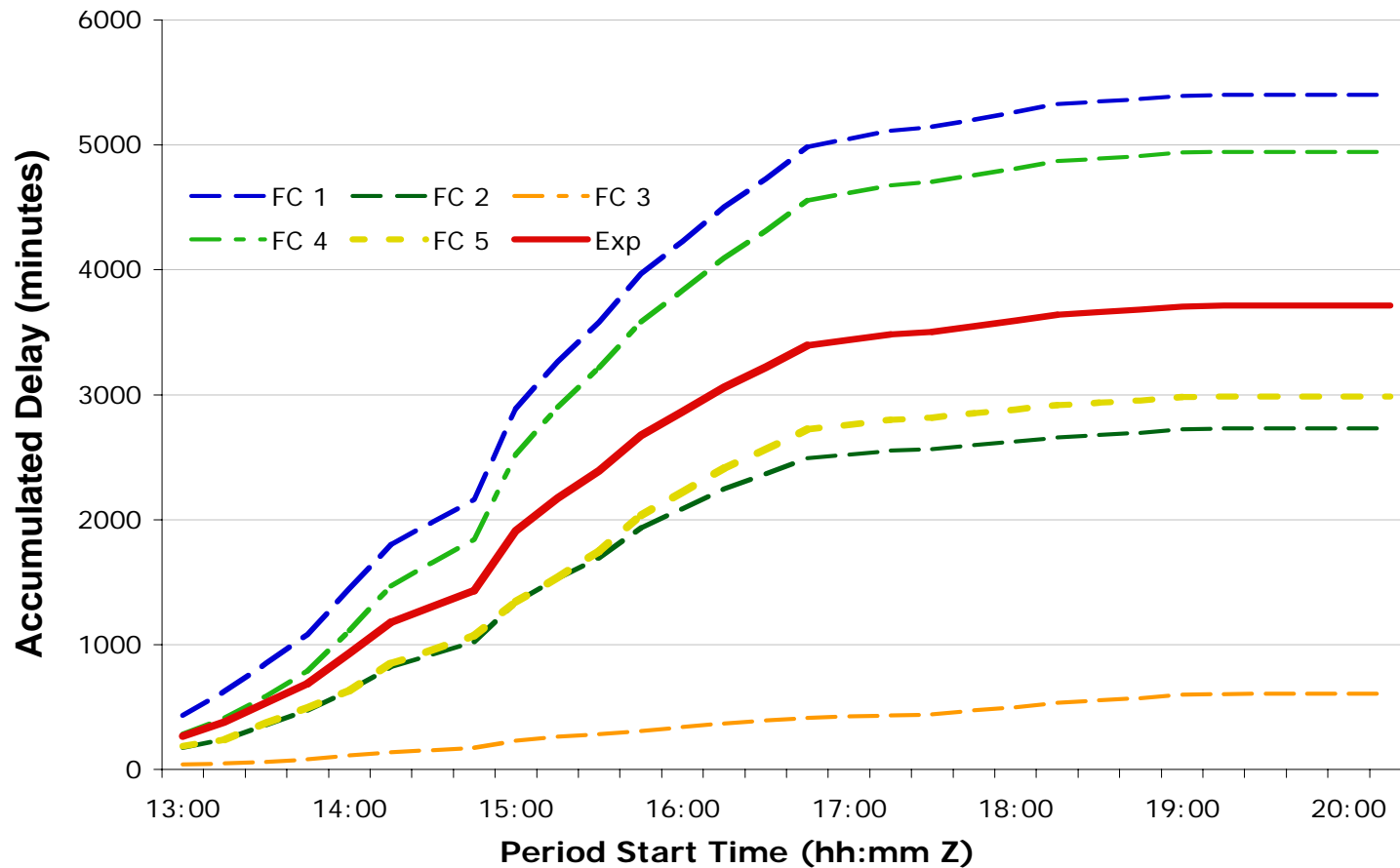
# Cumulative Delay Cost

## Total Delay Cost by Capacity Profile



# Unavoidable delay and critical decision times

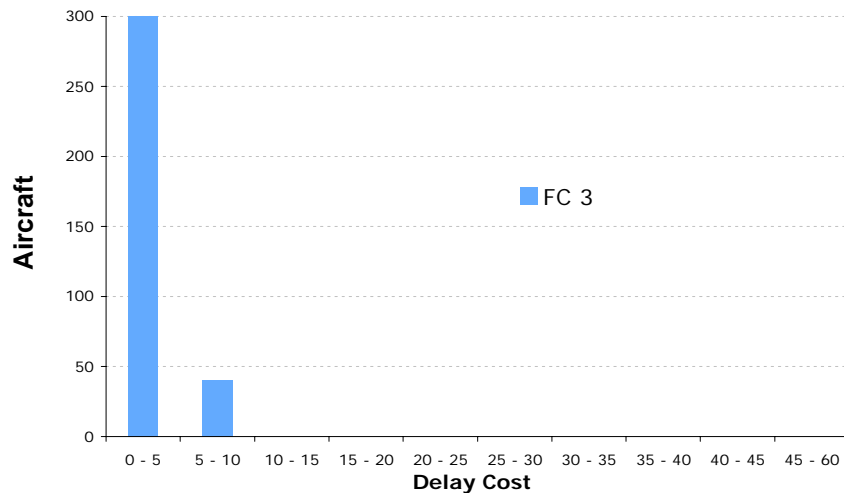
## Cumulative Unavoidable Delay for the Proposed GDP



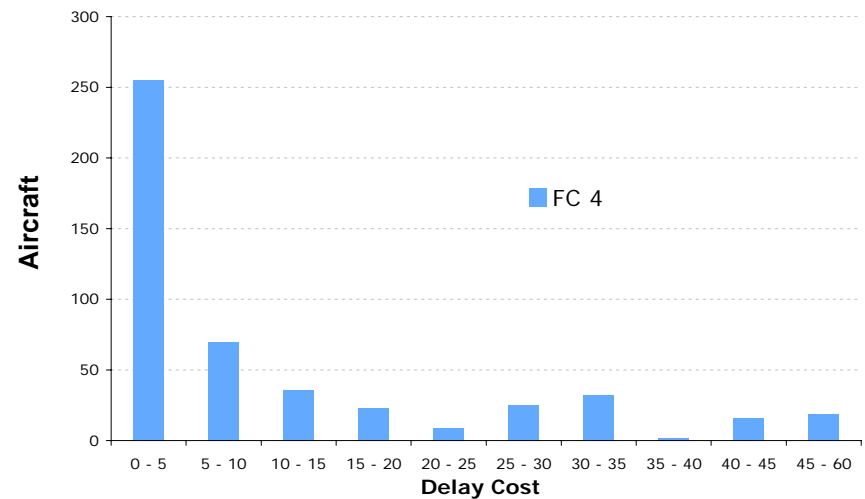
# Flight delay distribution

- The distribution of delay cost will vary by outcome
  - FC 3 has a tight distribution
  - FC 4 assigns heavy delay costs to some flights
  - But... delay cost, as with demand and capacity, should vary

Distribution of Total Delay Cost by Flight

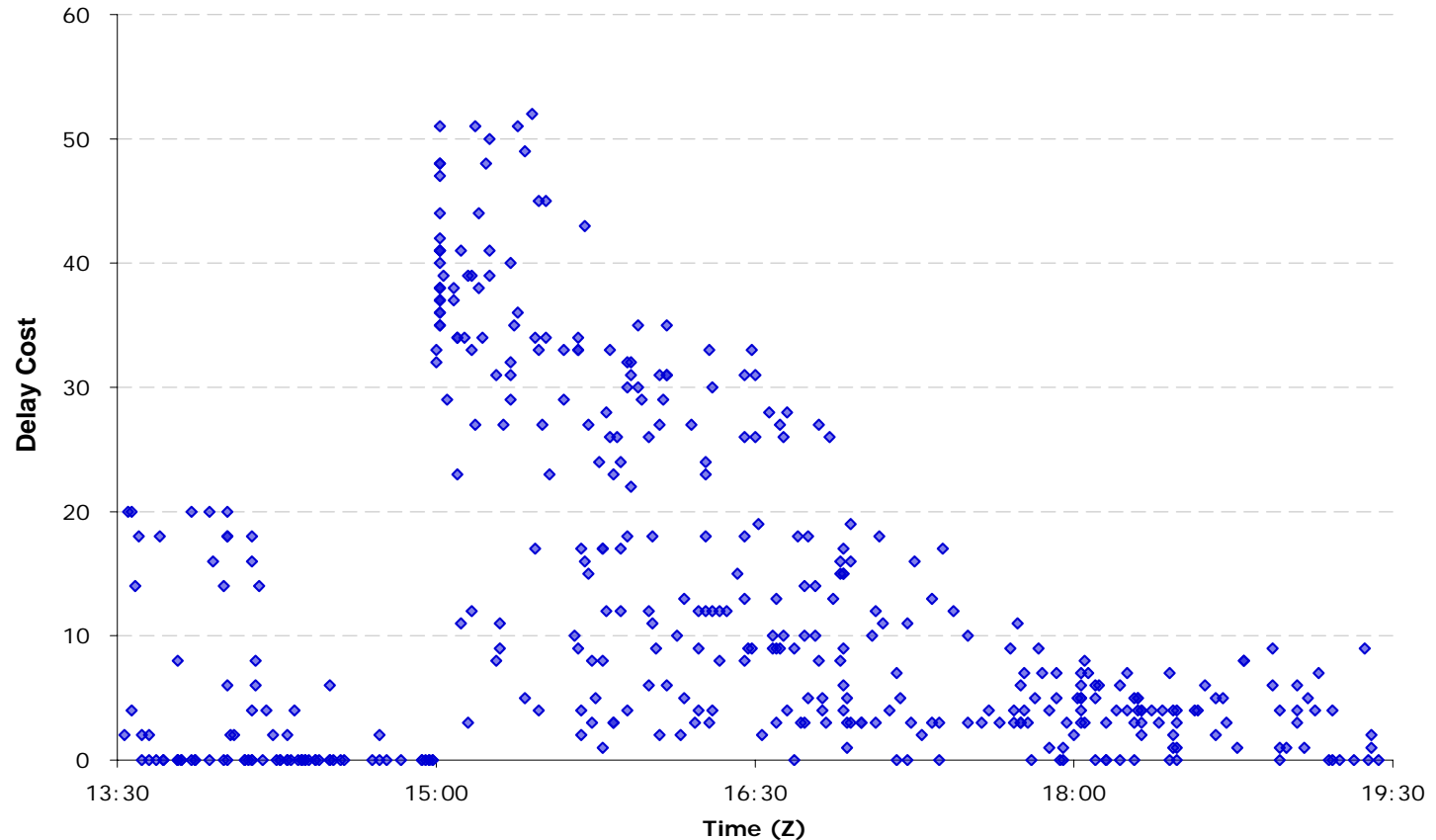


Distribution of Total Delay Cost by Flight



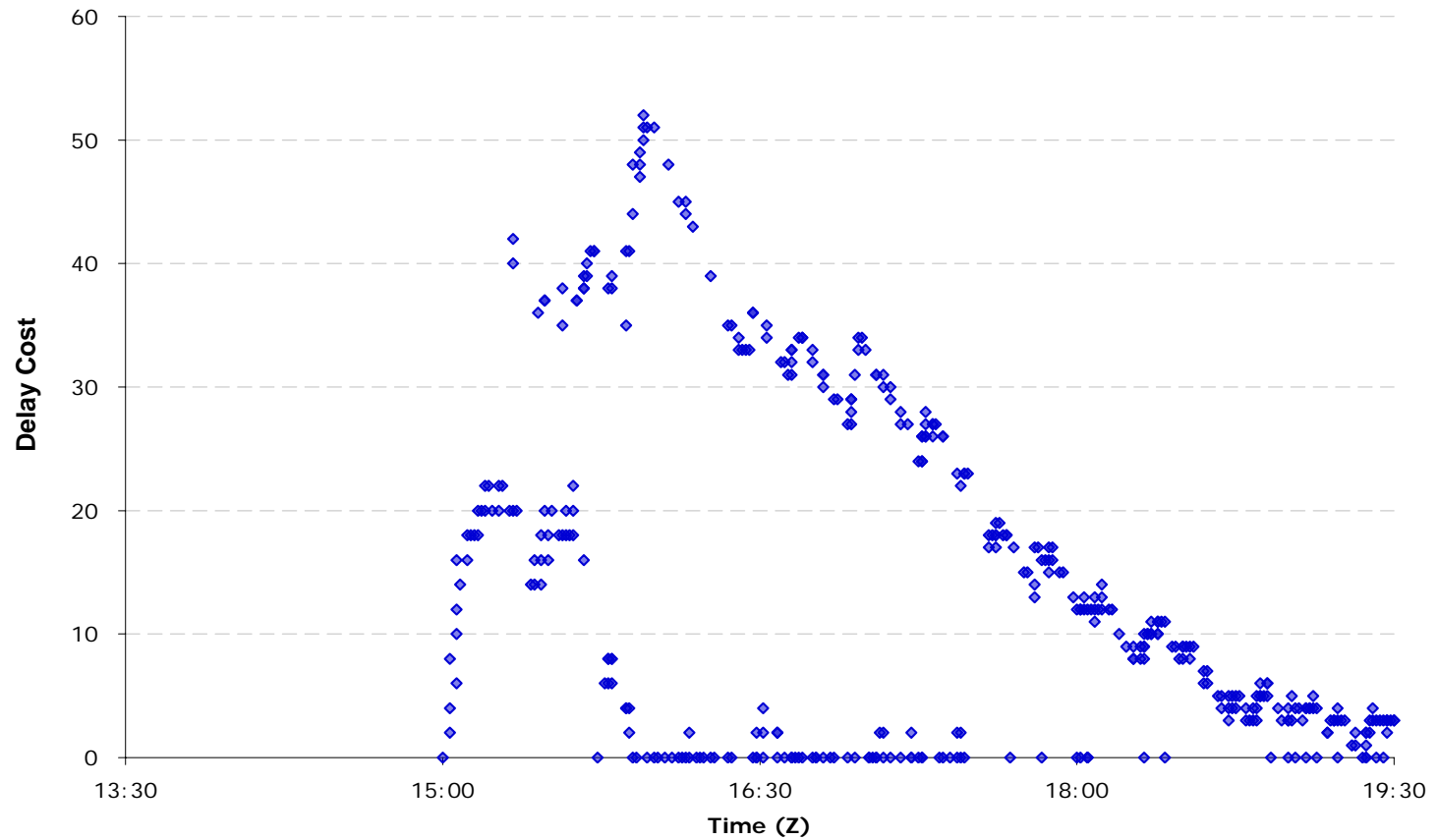
# Flight delay by scheduled departure time

Delay Cost by Scheduled Departure Time for FC 1



# Flight delay by scheduled arrival time

Delay Cost by Scheduled Arrival Time for FC 1



# Conclusions

- Optimization can be used to design GDPs
  - Offers an opportunity to improve the program
- Optimization techniques, however, are not the complete answer
  - Solutions do not consider important elements such as equity
  - Cannot guarantee many external constraints
  - May allow for the possibility of extreme outcomes
- It is important to have additional information
  - Other decision support tools can evaluate the proposed GDP
  - Optimization can be used as part of a larger process

# Further research

- Improve decision-making process
  - Design LPs to address system loads
  - Design decision support tools and a process to incorporate them
- Define GDP design objectives
  - Cost functions should allow non-linear / aggregate delay costs
  - Equity should be defined within the GDP context
- Improve system modeling
  - Account for stochastic, dynamic demand
  - Model operator behavior for popups and cancellations
  - Further information from capacity profiles?

# Methodology

- The design of a GDP must be approached from both a social and a technical perspective
- Improve understanding of the system
  - How decisions are made
    - Interview traffic managers at the FAA
  - How stakeholders are affected
    - Interview operation managers at different airlines
- Reformulate a model to capture new elements
- Define the role that optimization/models have in the overall GDP design process

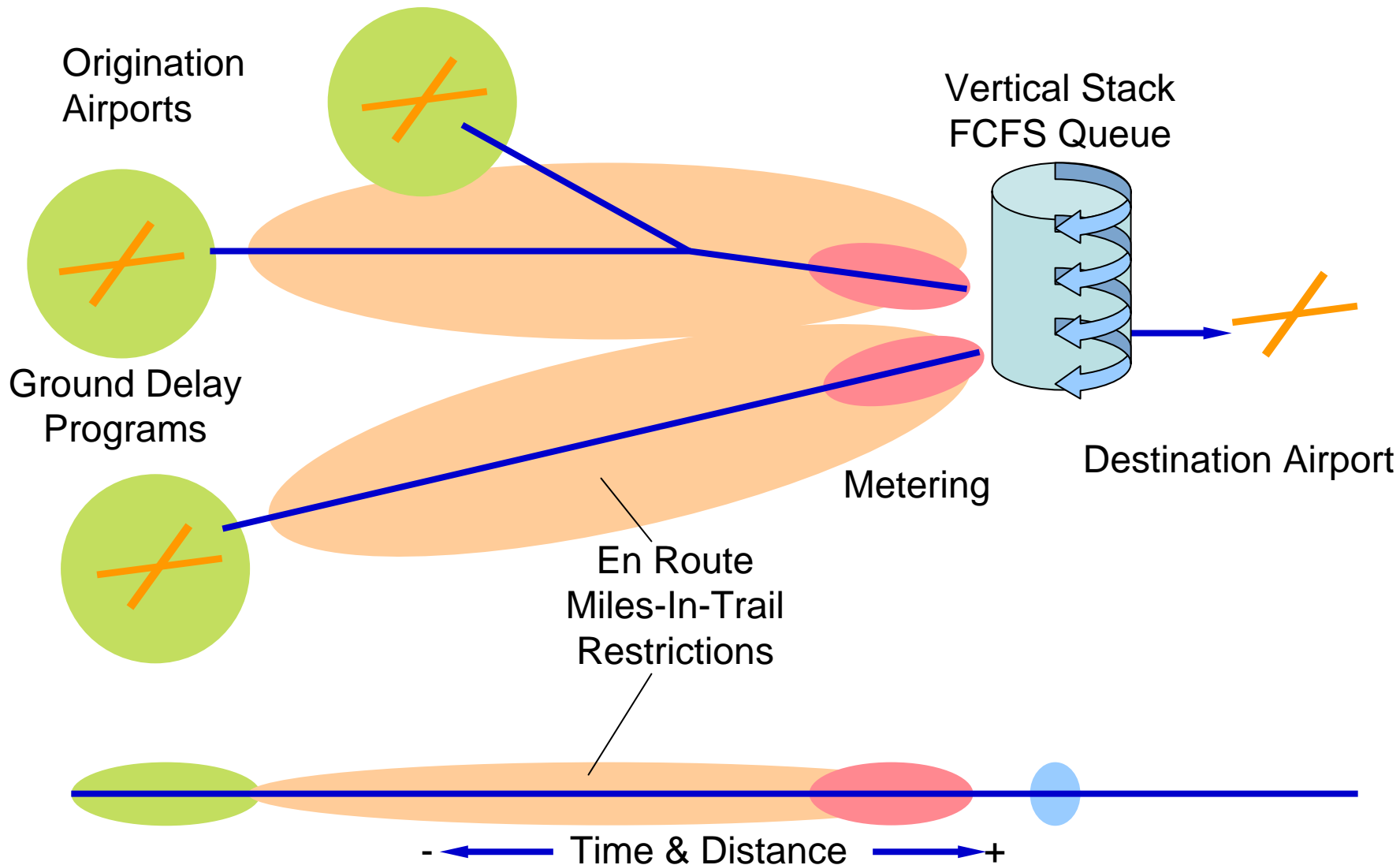
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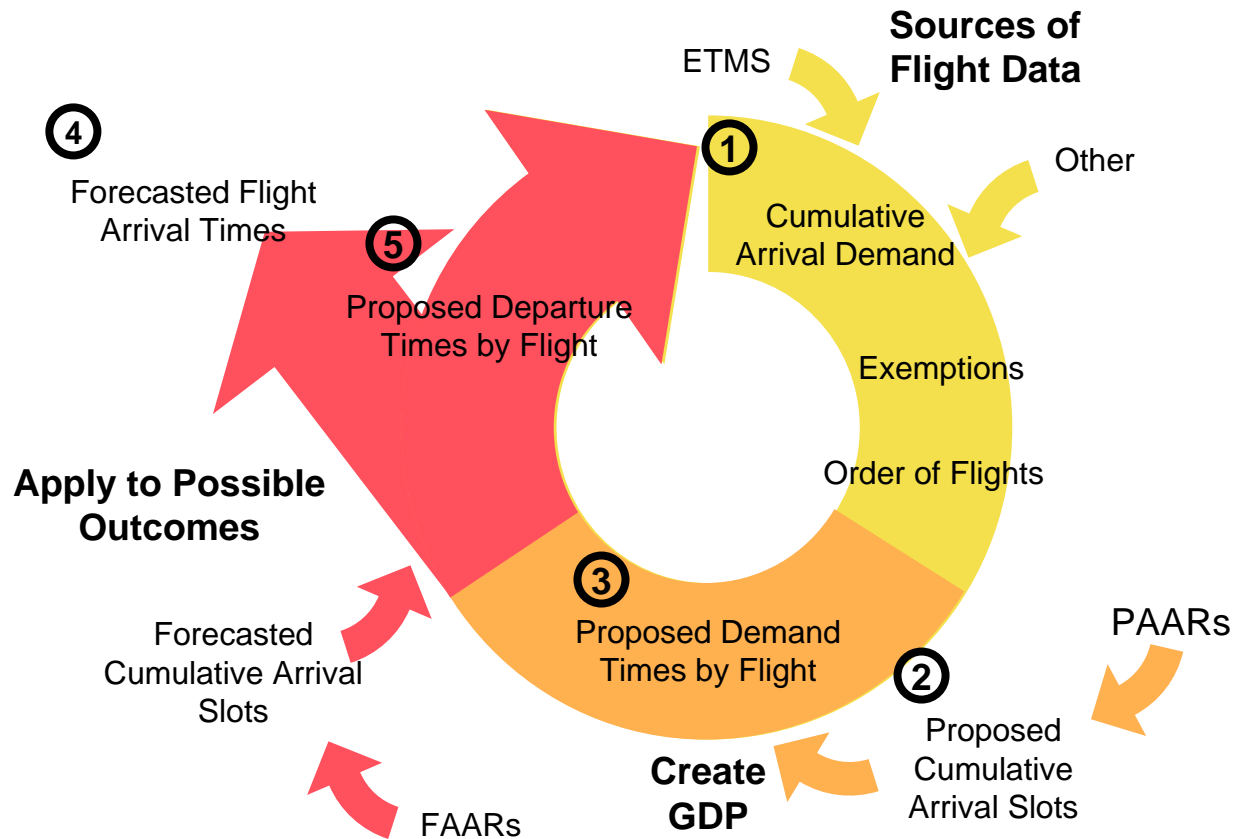
# Appendix Table

- Key assumptions
- Stages/scenario clarification
- 1993 Odoni-Richetta formulation
- 2005 Mukherjee formulation
- Processing LP output into revised departure times
- Data calculation in the Hanowsky tool
- Different ATFM techniques
- Map of ARTCC boundaries
- Time and information tradeoff
- Categorization of sources of delay
- Relative ground/air cost functions
- Actual ground/air cost functions
- Relevant flight times

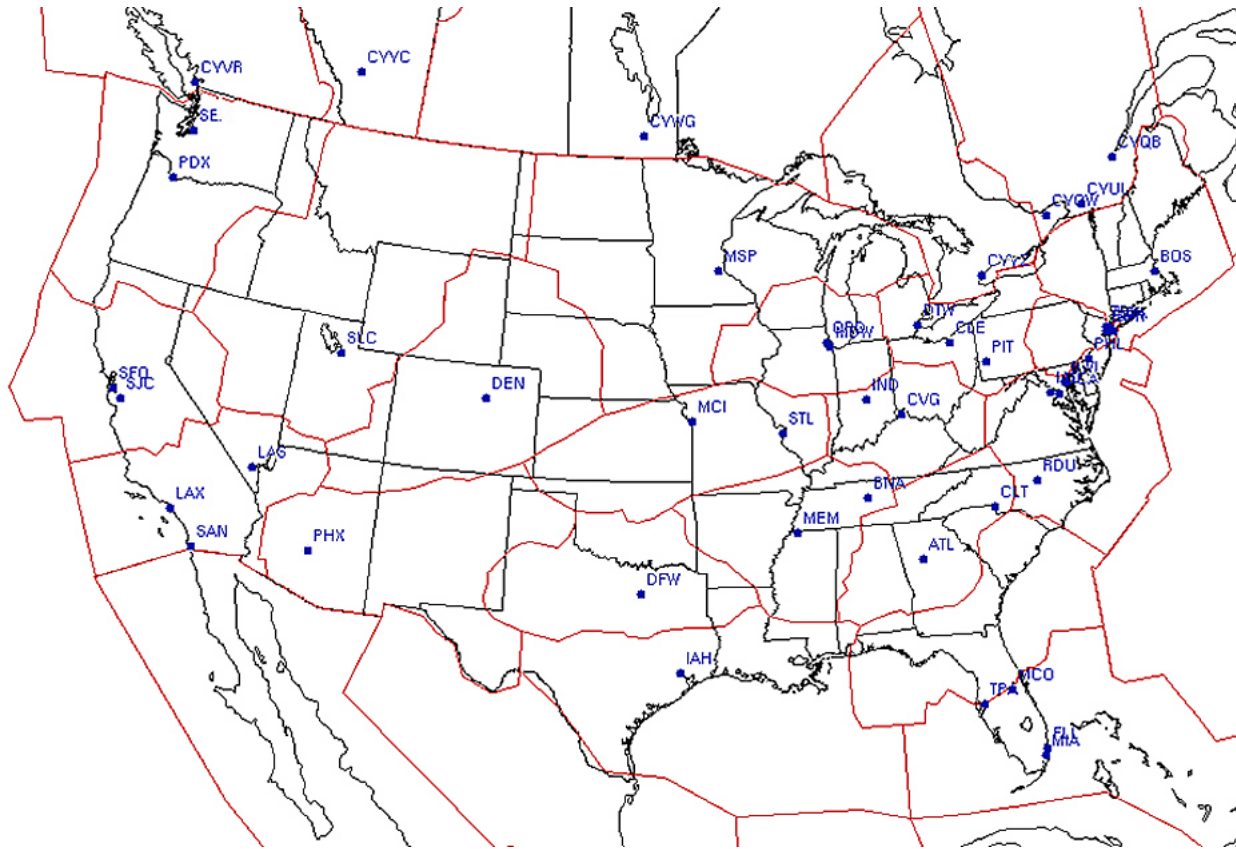
# Ground Delay Programs require more advance planning than other ATFM tools



# Calculation and data flows in the Excel tool

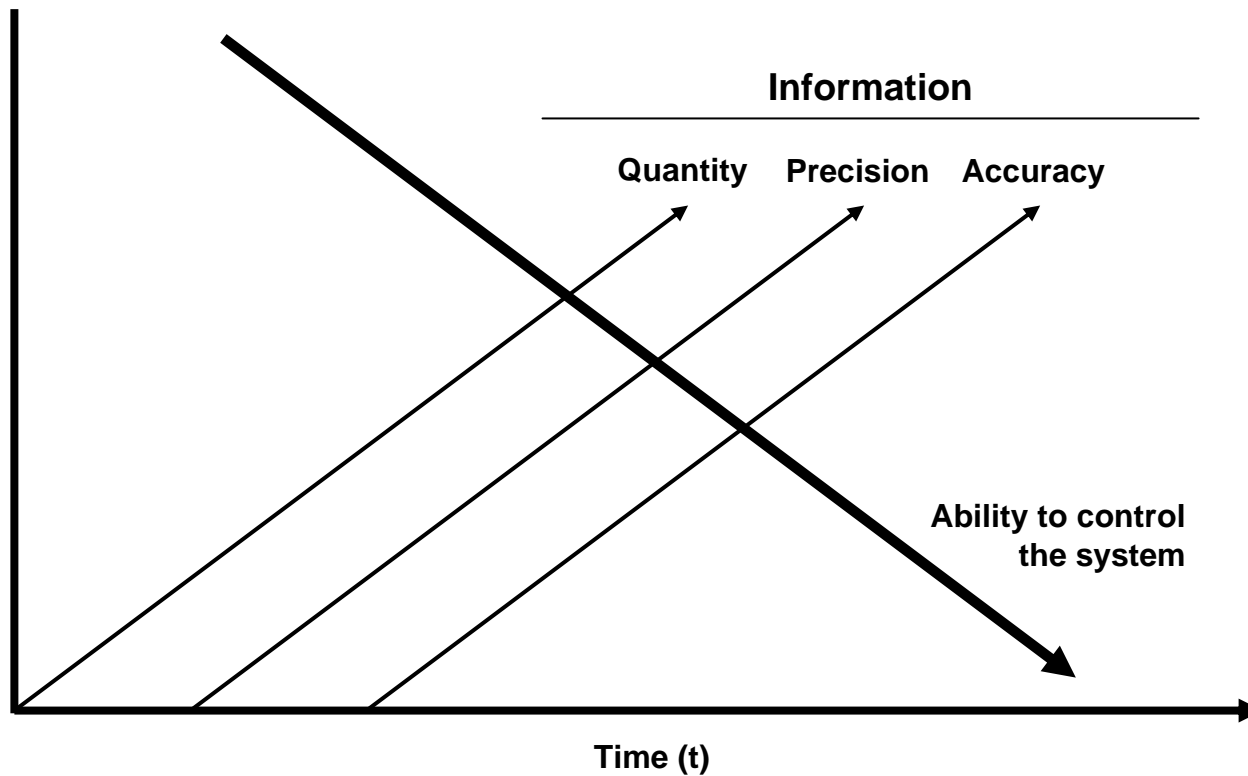


# Map of the US with standard ARTCC boundaries

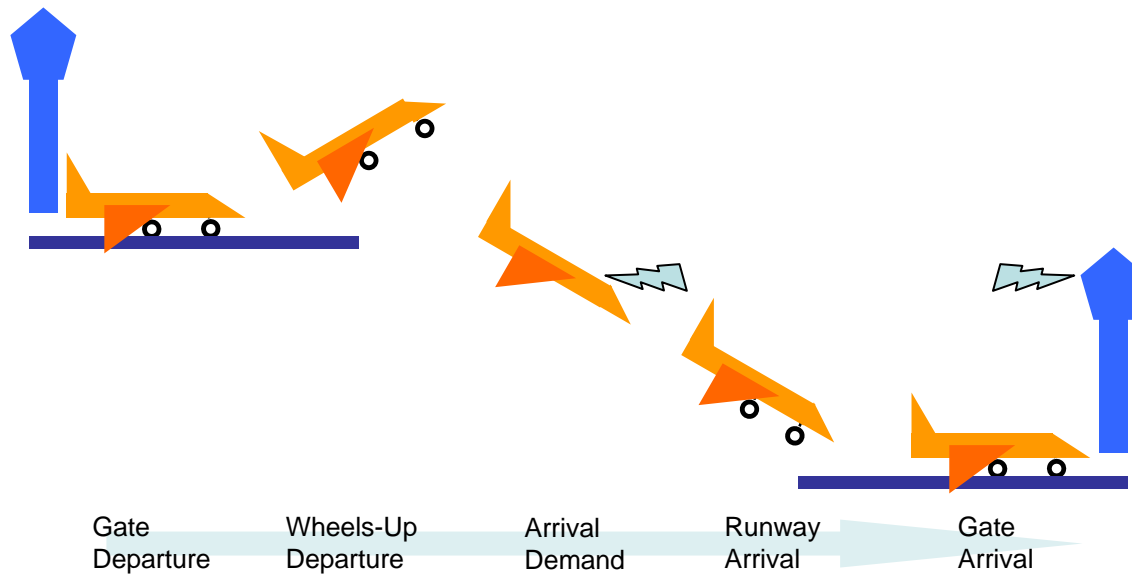


Source: Traffic Situation Display software (FAA), edited by the author using Adobe Photoshop

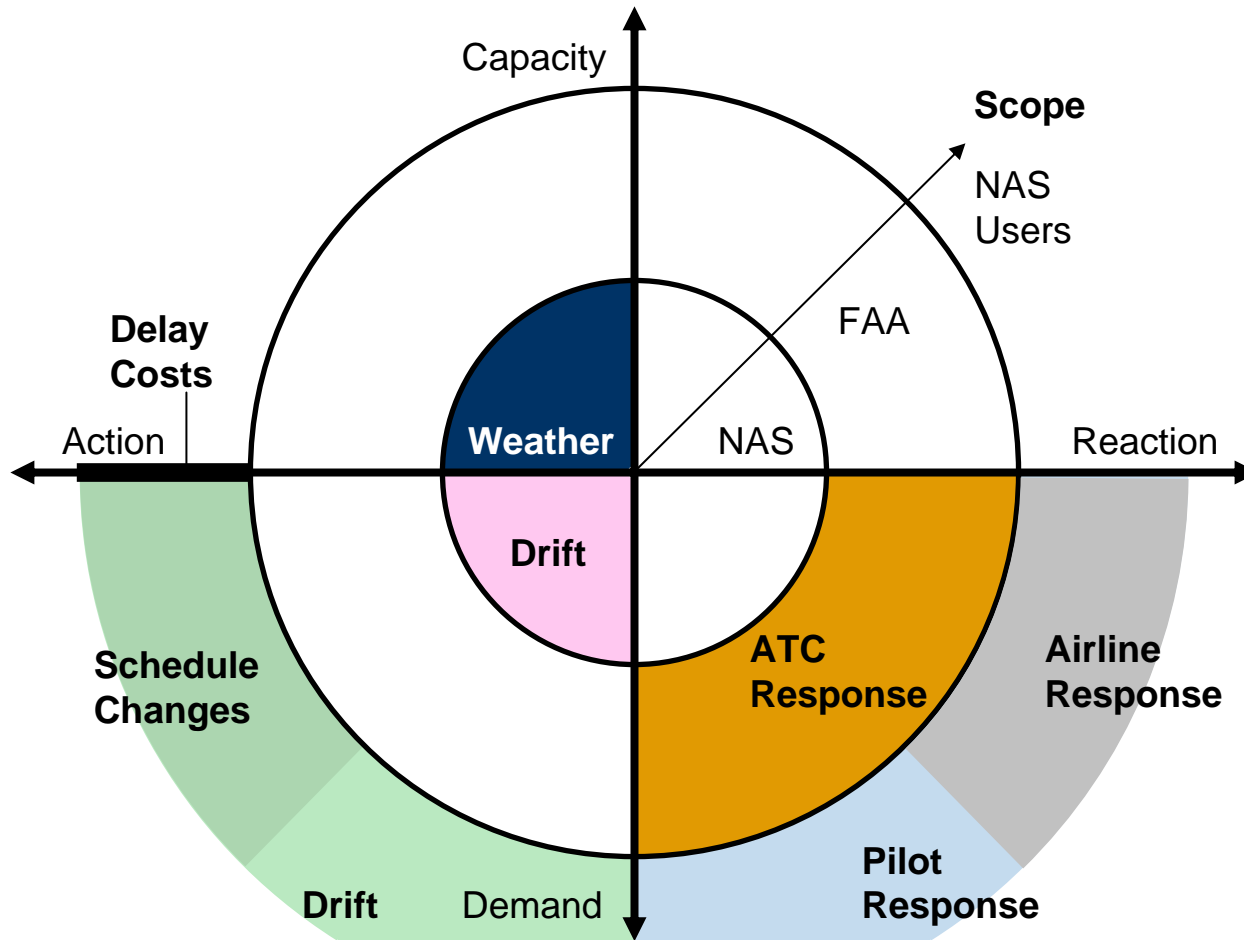
# The relationship between time and information



# Flight times relevant to ETMS arrival demand forecasts



# Categorization of delay sources



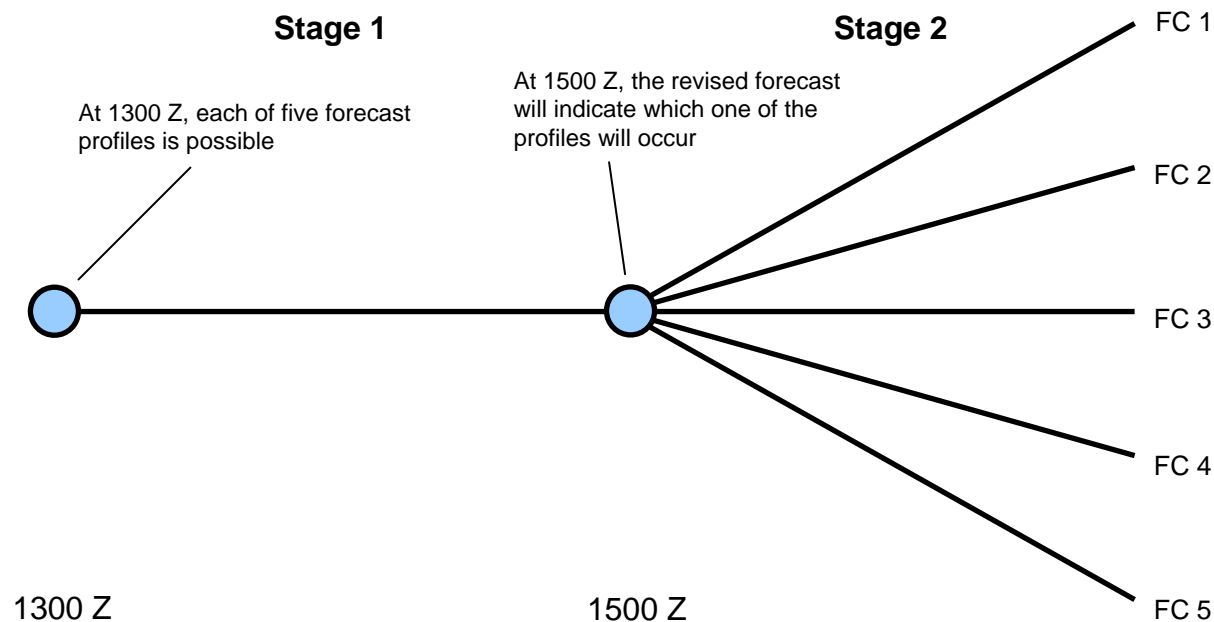
# Recent Literature: There is an opportunity

- Uncertain forecast arrival capacities can be quantified
  - MIT Lincoln Laboratory (2004): use airport-specific meteorological data
  - Hansen and Liu (2006): use historical AARs
- Linear programming techniques can model GDPs with uncertain arrival capacities
  - Odoni and Richetta (1993): stochastic and dynamic conditions
  - Mukherjee and Hansen (2004): aircraft based model
- GDPs with uncertain arrival capacities can be analyzed
  - Hanowsky (2006): Analysis of GDPs with uncertain capacity

**Existing literature does not discuss the application of optimization models**

# The system is dynamic

- Flight arrival demand changes
- Information on arrival capacity improves
  - Limited by the “two-stage” decision model



# Odoni-Richetta (1993): 2 stages and 1 aircraft class

Minimize: 
$$\sum_{q=1}^Q p_q \left\{ \sum_{s=1}^2 \sum_{i=t_s+1}^T \sum_{j=i+1}^{T+1} C_g (j-i) \times \chi_{qsij} + C_a \sum_{i=1}^T W_{qi} \right\}$$
 **Minimize Cost**

Subject to: 
$$\chi_{11ij} = \chi_{21ij} = \dots = \chi_{Q1ij} \quad \forall i = t_s + 1 \dots T; i \leq j \leq T + 1$$

$$\sum_{j=i}^{T+1} \chi_{qsij} = N_{si} \quad \forall s = 1 \dots 2; i = t_s + 1 \dots T; q = 1 \dots Q$$
 **Solve each decision**

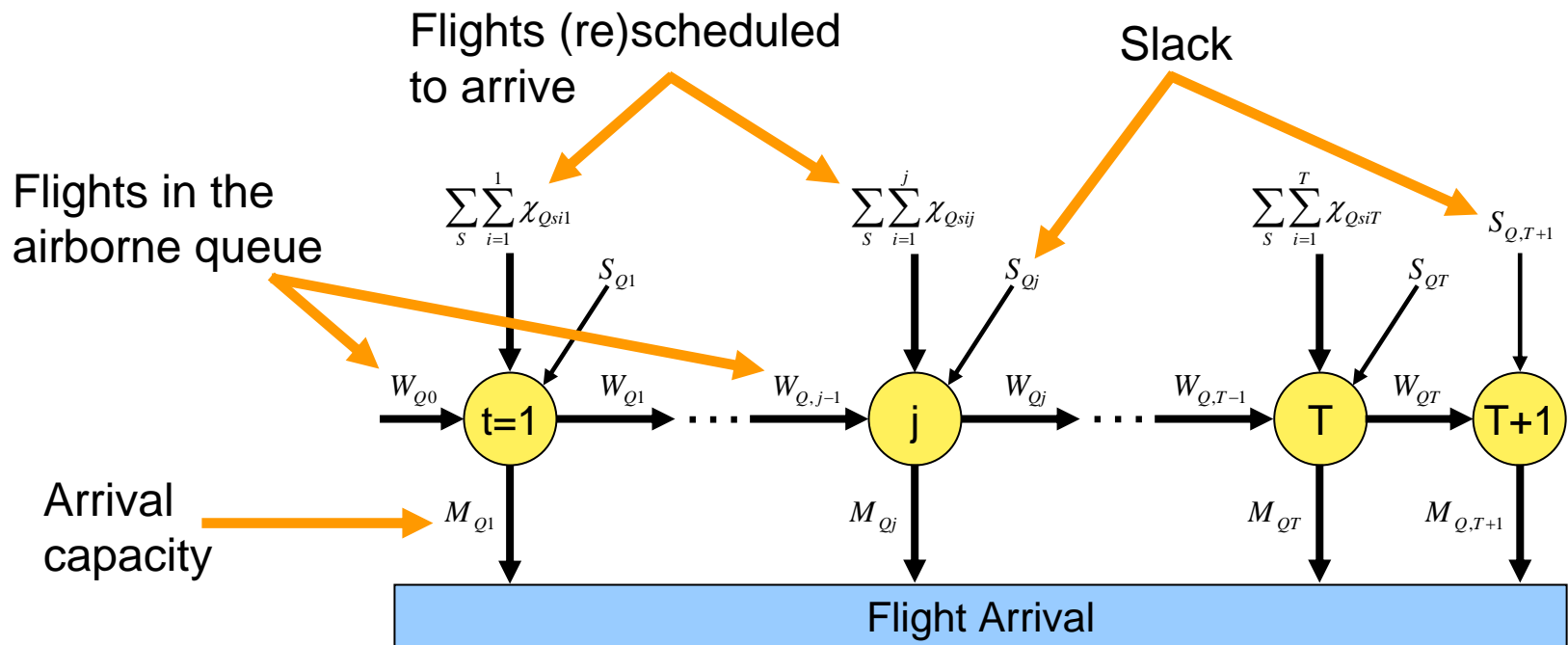
$$\sum_{i=1}^{T+1} S_{qi} = \sum_{i=1}^T M_{qi} \quad \forall q = 1 \dots Q$$

$$M_{qj} + W_{qj} = W_{qj-1} + \sum_{s:t_s < j} \sum_{i=t_s+1}^j \chi_{qsij} + S_{qj} \quad \forall j = 1 \dots T + 1; q = 1 \dots Q$$
 **Conserve Flow**

$$W_{q0} = W_{qT+1} = 0$$

$$\chi_{qsij}, W_{qi}, S_{qi} \geq 0$$

# The formulation is an adapted network flow model



$$M_{qj} + W_{qj} = W_{qj-1} + \sum_{s: t_s < j} \sum_{i=1}^j \chi_{qsij} + S_{qj} \quad \forall j = 1 \dots T+1; q = 1 \dots Q$$

# LP Results: Wait for more information

- Only limited delays are assigned to flights that depart before 1500 Z
  - 23 flights
  - 2 hours cumulative delay
    - Delays shown in h:mm
    - Aircraft operator codes have been masked
- Delay assigned to flights that depart after 1500 Z depends on the capacity of stage 2
- Objective function value
  - Two-Stage: 3,820 a/c-delay min
  - One-Stage at 1500 Z: 3,845 a/c-delay min
  - No GDP: 7,356 a/c delay min

Flight	Delay
10A321	0:01
01A1840	0:01
53A1214	0:26
10A727	0:21
53A534	0:02
01A1476	0:01
53A132	0:14
48A46	0:01
40A8083	0:01
53A1114	0:03
53A783	0:15
53A570	0:14
01A2332	0:02
53A8173	0:02
53A1144	0:04
44A800	0:02
53A8124	0:03
54A1825	0:06
01A2325	0:01
01A1311	0:02
09A1	0:02
48A128	0:01
46A908	0:01
<b>Total</b>	<b>2:06</b>

# System Load

- Objective
  - FAA defines specific system load standards to ensure safety
    - Strict limits on the number of aircraft
      - in a sector
      - under the responsibility of one controller
- ...and Subjective
  - Not always easy to predict whether a future time/location will meet this standard
    - Flight location, speed uncertain
    - The FAA can apply other techniques to reduce demand

# Efficiency

- Efficiency
  - Maximization of use of system, minimize “cost”
  - Scarce resources:
    - Fuel
    - Time
    - Airspace
- LPs can maximize an objective function  
...but can an appropriate objective function be identified?

# Equity

- Very subjective
- Define equity by how the FAA views the system
  - All aircraft are treated independently and identically
  - Aircraft size, economy, passenger load... \*not\* considered

**Do GDPs assign delays to some flights more than others?**

**Do GDPs assign more delays to some carriers than others?**

- There are many other ways to define equity
  - Passengers, system efficiency

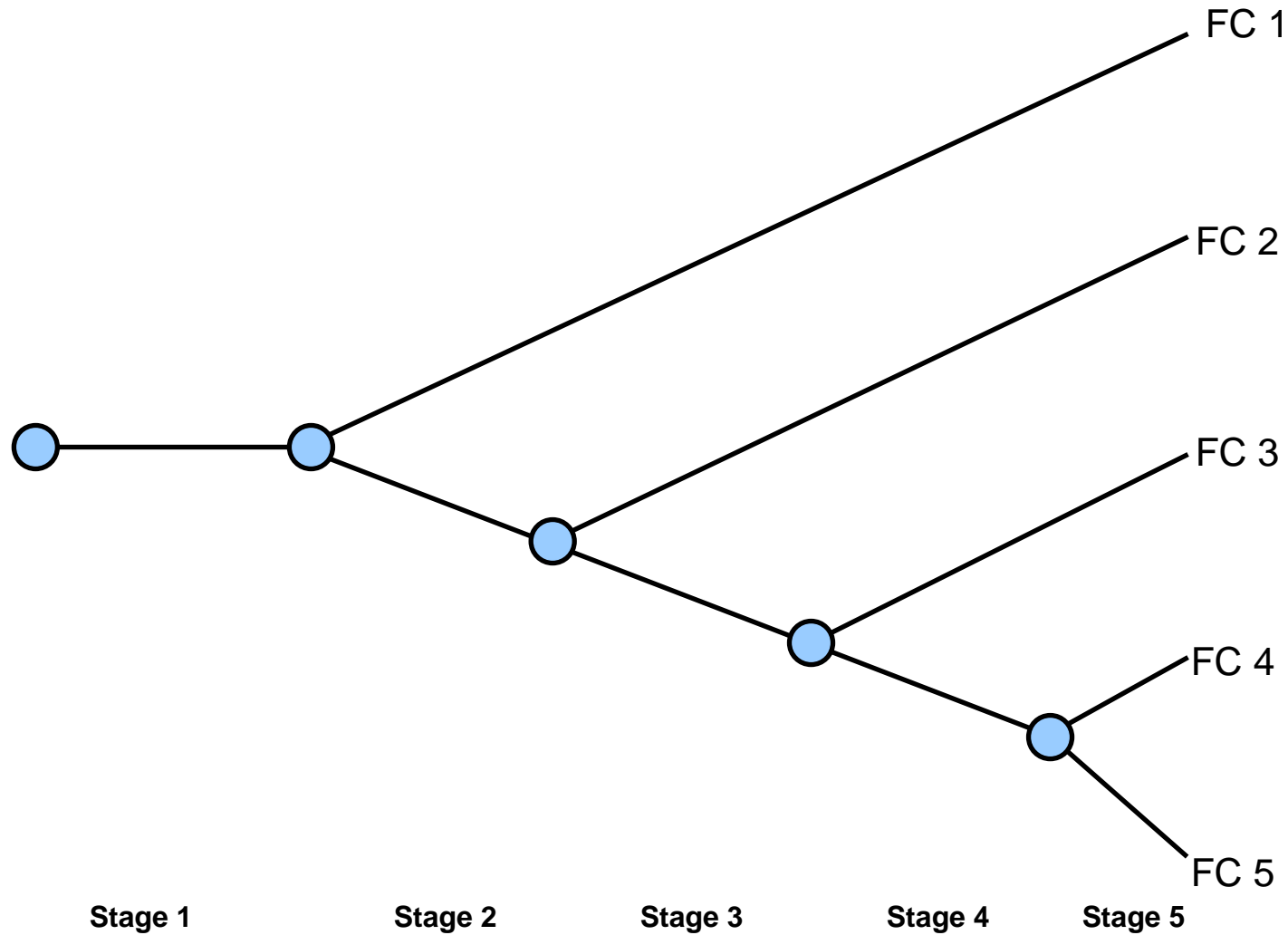
# Key Assumptions

- En route times are deterministic and constant
  - Drift, en route congestion, other ATFM strategies
- Demand is constant
  - Popups, cancellations
- Flight arrival order is processed as a single FCFS D/D/1 queuing system
  - Multiple runway system, tactical ATFM
- Air carriers will adhere to assigned departure times
  - NavCanada

# Subjective Criteria

- GDPs are designed by traffic managers at the FAA
  - A framework is used to guide decisions
  - No optimization tools are used
- “Safe and efficient”
- Equitable
  - Idea: Are programs sustainable?
  - Do users receive more benefits than costs?

# Example of stages/scenarios



# Full Odoni Richetta (1993) formulation

Minimize: 
$$\sum_{q=1}^Q p_q \left\{ \sum_{k=1}^K \sum_{s=1}^Q \sum_{i=t_s+1}^T \sum_{j=i+1}^{T+1} C_g(k, j-i) \times \chi_{qksij} + c_a \sum_{i=1}^T W_{qi} \right\}$$

Subject to: 
$$\chi_{sksij} = \chi_{s+1ksij} = \dots = \chi_{Qksij} \quad \forall s = 1 \dots Q-1; i = t_s + 1 \dots T; i \leq j \leq T+1; q = 1 \dots Q; k = 1 \dots K$$

$$\sum_{j=i}^{T+1} \chi_{qksij} = N_{ksi} \quad \forall k = 1 \dots K; s = 1 \dots Q; i = t_s + 1 \dots T$$

$$\sum_{i=1}^{T+1} S_{qi} = \sum_{i=1}^T M_{qi}$$

$$W_{qi} - W_{q(i-1)} - \sum_{k=1}^K \sum_{s:t_s < i} \sum_{j=t_s+1}^i \chi_{qksji} - S_{qi} = -M_{qi} \quad \forall i = 1 \dots T+1$$

$$W_{q0} = W_{q(T+1)} = 0$$

$$\chi_{qksij}, W_{qi}, S_{qi} \geq 0$$

# Avijit Mukherjee (2005) formulation (UC Berkeley PhD Thesis)

Minimize: 
$$\sum_{q \in \Theta} P(q) \times \left\{ \sum_{f \in \Phi} \sum_{t=Arr_f}^{T+1} (t - Arr_f) \times (\chi_{f,t}^q - \chi_{f,t-1}^q) + \lambda \times \sum_{t=1}^T w_t^q \right\}$$

Subject To:

$$\chi_{f,t}^q - \chi_{f,t-1}^q \geq 0$$

$$w_{t-1}^q - w_t^q + \sum_{f \in \Phi} (\chi_{f,t}^q - \chi_{f,t-1}^q) \leq M_t^q$$

$$w_0^q = w_{T+1}^q = 0$$

$$\chi_{f,T+1}^q = 1$$

$$Y_{f,t}^{S_1^i} = Y_{f,t}^{S_k^i} = Y_{f,t}^{S_{N_i}^i} \quad \forall f \in \Phi; t \in \{1 \dots T\}; S_k^i \in \Omega_i : N_i \geq 2, \sigma_i \leq t \leq \mu_i$$

# Delay assignment (based on the Odoni-Richetta formulation)

- Ground delays are assigned based upon underlying FAA methodology: FCFS by aircraft
  - Consider five flights in stage 1 (13:00 to 15:00) with arrivals between 15:00 Z and 15:04 Z.
  - LP output:  $\chi_{25,25} = 3$  and  $\chi_{25,27} = 2$

Flight	Dep Time	Arr Time
A1	14:00 Z	15:00 Z
A2	14:22 Z	15:01 Z
A3	13:00 Z	15:02 Z
A4	13:45 Z	15:03 Z
A5	13:00 Z	15:04 Z

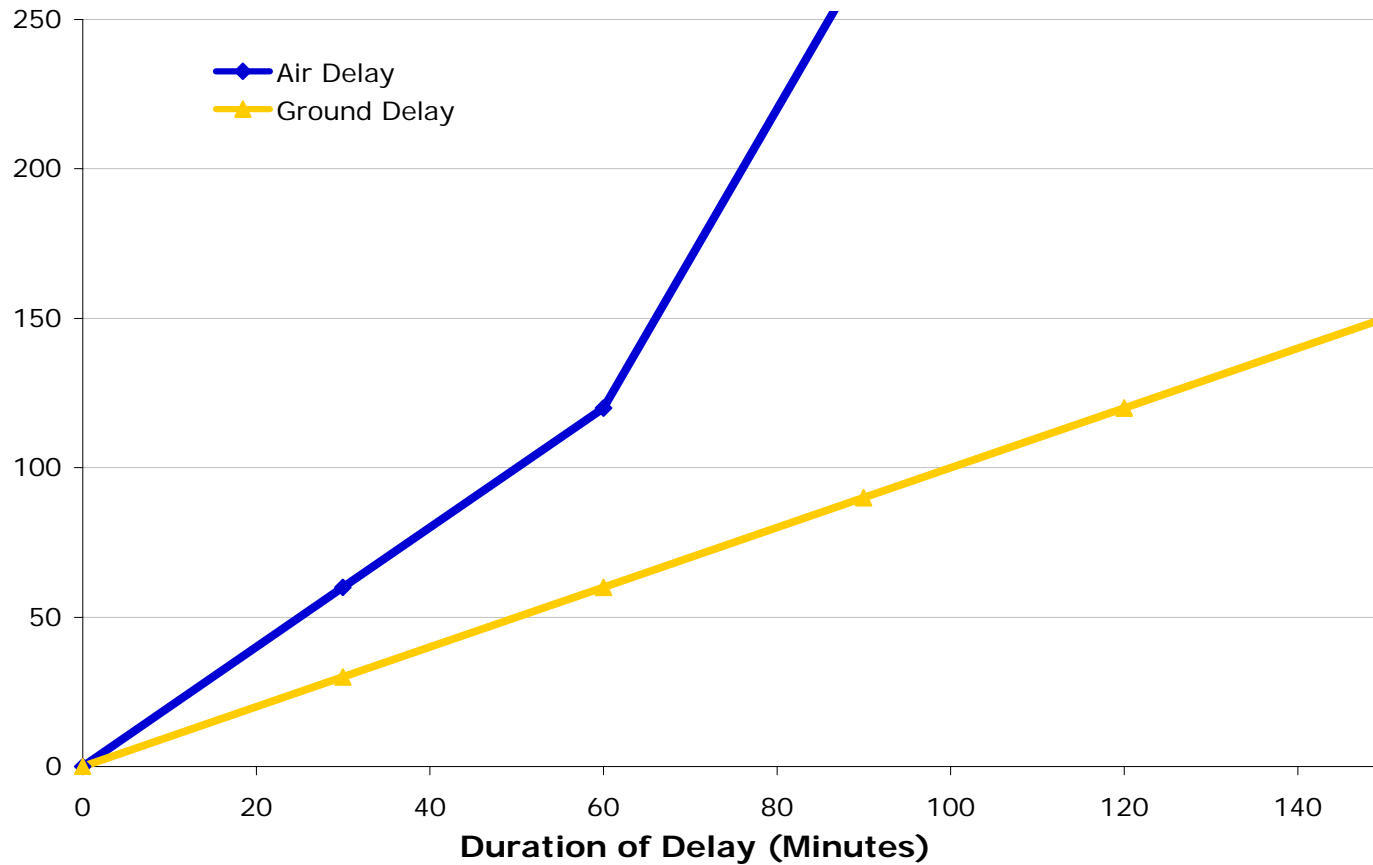
Flight	Rev Arr	Rev Dep
A1	15:00 Z	14:00 Z
A2	15:01 Z	14:22 Z
A3	15:02 Z	13:00 Z
A4	15:10 Z	13:52 Z
A5	15:10 Z	13:06 Z

Gnd Delay
0:00
0:00
0:00
0:07
0:06

- Arrival times are assigned FCFS
- For delayed flights, the revised arrival times are at the beginning of the new arrival period
- En route time is assumed to be constant

# One possible set of ground and air cost functions

Cumulative Delay Cost by Duration of Delay (Units)



# Air, ground, and total cost functions

